

INA ACTUATORS WITH 2 & 4 STACK MOTORS FOR MAXIMUM CONTINUOUS FORCE

The IMA Integrated Servo Actuator product offering now includes 2 and 4-stack motors in addition to the standard 1 and 3-stack motor offerings.

IMA Servo Integrated Actuator benefits include:

• Compact, modular design with an integrated servomotor with simple installation for efficient machine design

• Precise motion control

Best In Class Force and Process Repeatability with Skewed
Stator Design

Best in class force repeatability independent of
rotor position

•Low cogging torque and reduced torque ripple

> Quick and easy integration with drive and control systems

IMA33: 4-stack motor windings result in up to 38% more continuous force over 3-stack windings in the IMA 44 IMA44: 4-stack motor windings result in up to 84% more continuous force over 3-stack windings

IMA Integrated Linear Servo Actuators with Tolomatic Roller Screws for Long, Reliable Life Pre-loaded roller screws benefits:

• Dynamic applications (high frequency)

Increased peak force and DLR with XR Roller Screw design

- Longer rollers for increased capability
- Peak force up to 5400 lbf (24kN)
- DLR up to 20,624 lbf (92 kN)

LINEAR SOLUTIONS MADE EASY

IMA - Linear Actuator with Integrated 2-4 Stack Servo Motor



Tolomatic

IMA - Linear Actuator with Integrated 2-4 Stack Servo Motor

Performance & Mechanical Specifications:

SERIES	STACK ¹	NUT/ Screw	SCRE	N LEAD	RAT	IC LOAD TING . REVS)	CONT.	THRUST	PEAK T	HRUST	MAX. VE	LOCITY	BASE II	VERTIA ²
			mm	in	kN	lbf	kN	lbf	kN	lbf	mm/sec	in/sec	kg-cm ²	lb-in ²
		BN05	05	0.197	8.7	1,960	4.5	1,000	4.5	1,000	350	13.8	5.8261	1.9909
		BN10	10	0.394	5.4	1,215	2.8	640	4.0	900	700	27.6	5.8261	1.9909
IMA33	4	BN20	20	0.788	11.4	2,560	1.4	320	3.0	675	1,333	52.5	5.9428	2.0308
Ĭ	4	RN04	04	0.157	41.1	9,240	6.6	1,475	11.1	2,500	280	11.0	5.8310	1.9926
		RN05	05	0.197	45.4	10,210	5.3	1,180	11.1	2,500	350	13.8	5.8310	1.9926
		RN10	10	0.394	45.4	10,210	2.6	590	10.2	2,290	700	27.6	5.8310	1.9926
		BN05	05	0.197	18.0	4,035	5.5	1,245	10.4	2,345	292	11.5	7.9631	2.7211
		BN10	10	0.394	15.0	3,370	2.8	625	8.3	1,865	583	23.0	7.9631	2.7211
	2	BN25	25	0.985	11.3	2,540	1.1	250	3.3	745	1,333	52.5	7.9631	2.7211
	2	RN04	04	0.157	56.5	12,705	6.4	1,440	17.8	4,000	233	9.2	7.8865	2.6949
		RN05	05	0.197	56.5	12,705	5.1	1,150	14.7	3,300	292	11.5	7.8865	2.6949
		RN10	10	0.394	56.5	12,705	2.6	575	7.7	1,725	583	23.0	7.8865	2.6949
IMA44	3	RN05XR	05	0.197	56.5	12,705	7.3	1,650	17.8	4,000	292	11.5	9.6021	3.2812
l₹		BN05	05	0.197	18.0	4,035	10.4	2,345	10.4	2,345	333	13.1	11.8405	4.0461
		BN10	10	0.394	15.0	3,370	7.3	1,645	11.0	2,470	667	26.2	11.8405	4.0461
		BN25	25	0.985	11.3	2,540	2.9	660	8.8	1,975	1,333	52.5	11.8405	4.0461
	4	RN04	04	0.157	56.5	12,705	16.9	3,810	17.8	4,000	267	10.5	11.7638	4.0199
		RN05	05	0.197	56.5	12,705	13.6	3,045	14.7	3,300	333	13.1	11.7638	4.0199
		RN10	10	0.394	56.5	12,705	6.8	1,525	17.8	4,000	667	26.2	11.7638	4.0199
		RN05XR	05	0.197	56.5	12,705	13.6	3,045	17.8	4,000	333	13.1	11.7638	4.0199

Motor Specificat	ions:	IMA33 IMA44					
WINDING/MOTO	OR VOLTAGE	MV24	MV44	MV22	MV42	MV24	MV44
TORQUE	N-m/A Peak	0.64	1.28	0.52	0.90	0.64	1.29
CONSTANT (Kt)	in-lb/A Peak	5.7	11.4	4.6	8.0	5.7	11.4
VOLTAGE Constant (K _e)	V/Krpm Peak	78	155	66	107	81	162
CONTINUOUS	N-m	5.6	5.6	5.5	4.9	14.6	14.6
STALL TORQUE	in-lb	50.0	50.0	48.8	43.0	129.0	129.0
CONTINUOUS Stall Current	A _{RMS}	7.2	3.6	7.5	3.8	16.0	8.0
PEAK TORQUE			43.7				
FEAK TUNQUE	in-lb	194.0	194.0	146.0	129.0	387.0	387.0
PEAK CURRENT	A _{RMS}	29.0	14.5	22.5	11.4	48.0	24.0
RESISTANCE	Ohms	1.14	4.56	0.90	4.20	0.35	1.46
INDUCTANCE	mH	2.42	9.82	3.65	15.70	2.04	8.90
BUS VOLTAGE	V _{RMS}	230	460	230	460	230	460
SPEED @ RATED V	RPM	4,200	4,200	3,500	3,500	4,000	4,000
NO. OF POLES					3		

Performance data was validated using an aluminum face mount plate: IMA22 (8.25" x 7.0" x 0.7"); IMA33 (8.25" x 7.0" x 0.7"); IMA44 (9.0" x 9.0" x 0.7"); IMA55 (9.0" x 9.0" x 1.0") Ambient Temp. = $77^{\circ}F$ (25°C); Elevation < 3281' (1,000 m); Drive specifications: Sinusoidal Commutation and PWM Voltage Source

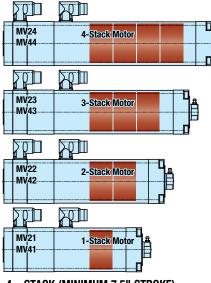
 $^{1}2$ = 2 Stack winding MV22 or MV42 3 = 3 Stack winding MV23 or MV43 4 = 4 Stack winding MV24 or MV44

²Value given is for a zero stroke actuator + To be determined, visit www.tolomatic. com for up-to-date information

³In all vertical application an unpowered IMA will require a brake to maintain position. Tolomatic recommends that the nominal back drive force specification be used for reference only. Back drive force is subject to change throughout the life of the actuator, due to mechanical break in, ambient temperature, and duty cycle variation.

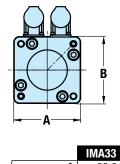


IMA - Linear Actuator with Integrated 1-4 Stack Servo Motor



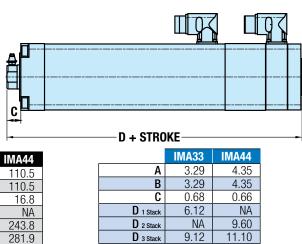
- 4 STACK (MINIMUM 7.5" STROKE)
- 3 STACK (MINIMUM 6" STROKE)
- 2 STACK (MINIMUM 4.5" STROKE)
- 1 STACK (MINIMUM 3" STROKE)

Dimensions



A	83.6	110.5
В	83.6	110.5
C	17.3	16.8
D 1 Stack	155.5	NA
D 2 Stack	NA	243.8
D 3 Stack	231.7	281.9
D 4 Stack	269.8	320.0
D 1 Stack w/ Brake	196.9	NA
D 2 Stack w/ Brake	NA	279.3
*D 3 Stack w/ Brake	273.1	317.4
*D 4 Stack w/ Brake	311.2	355.5
Dimensions in r	nillimeters	

C



D 3 SLAUK	0.12	11.10
D 4 Stack	10.62	12.60
D 1 Stack w/ Brake	7.75	NA
D 2 Stack w/ Brake	NA	11.00
*D 3 Stack w/ Brake	10.75	12.50
*D 4 Stack w/ Brake	12.15	13.90

Dimensions in millimeters

*Overall length reduction is possible depending on application, contact Tolomatic

NA = Not Available

The Tolomatic Difference Expect More From the Industry Leader:



Technology[™] for challenging applications.



Built-to-order with configurable stroke lengths and flexible mounting options.



Size and select electric actuators with our online software.



Match your motor to compatible mounting plates with Tolomatic actuators.



Dimensions in inches

Download 2D or 3D CAD files for Tolomatic products.



Get a guestion answered or request a virtual design consultation with one of our engineers.

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looma EXCELLENCE IN MOTION

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