

ServoWeld Actuators SWA & SWB MODELS



INTEGRAL MOTOR HIGH THRUST ACTUATOR

ServoWeld SWA & SWB

Tolomatic is the world's leading manufacturer of integrated servo actuators for resistance spot welding, used by the world's top weld gun OEM's and numerous global vehicle manufacturers.

Superior Integrated Servo Motor Actuators

Tolomatic's ServoWeld family of integrated servo actuators are designed for best-in-class performance with the factors that are most important for resistance spot welding gun applications.

NUMBER OF WELDS/ PRODUCT LIFE	Tolomatic's superior roller screw design has the highest dynamic load rating for more welds than any competitive technology (other roller screws, ball screw, pneumatic).
FORCE REPEATABILITY	Skewed winding designed for welding minimizes motor cogging and provides industry best actuator force repeatability: $\pm 3\%$ Over the Lifetime of the Actuator
EFFICIENCY	All elements of actuator (winding, screw, rod scraper, bearings) are designed to optimize the efficiency of the actuator system and provide the most energy efficient solution on the market.
WELDS/ MINUTE	All elements of the actuator (winding, screw, rod scraper, bearings) are designed to last and run as cool as possible in welding applications, with the ability to add water cooling as an option. This means more welds per minute than any competitive technology (other roller screws, ball screw, pneumatic).
WEIGHT	Tolomatic integrated servo actuators minimize weight when designed into the weldgun. Additionally, Tolomatic can customize actuators for a specific weldgun applications to provide industry leading light weight designs.
LIFETIME COST	By building the longest lasting, most efficient and highest weld per minute actuators on the market,



Typical Robotic ServoWeld Installation



Tolomatic Offers the Broadest, Most Capable Family of Integrated Servo Actuators for Resistance Spot Welding

Model:	GSWA	SWA/SWB	CSWX
Number of Welds ¹ (millions):	20+	20 + (10+ SWB)	30+ (20+ CSW)
Re-lubrication without Disassembly:	Yes ⁴	Yes	Yes
Peak Force:	36.7 kN [8,243 lbf]	24.0 kN [5,395 lbf] SWA 22.0 kN [4,950 lbf] SWB	18.0 kN [4,047 lbf] CSWX 15.6 kN [3,500 lbf] CSW
Actuator Output Force ² (Lifetime) Repeatability:	±3%	±3% (±5% SWB)	±3%
Weight (size 33,3) ³ (size 44,04) ³ (size 55) ³ :	8.3 kg [18.3 lb] 13.8 kg [30.4 lb] 30.5 kg [67.2 lb]	7.2 kg [15.9 lb] 14.2 kg [31.2 lb]	min: 10.2 kg [22.6 lb]
Water Cooling:	Optional	Optional	Optional
Manual Override:	Optional	No	Optional
Full Force Direction:	Push and Pull	Push	Push and Pull

¹ Based on properly lubricated ServoWeld unit used as recommended in user manual. Weld schedule, tip force, environment and lubrication are factors in the total number of welds achievable with ServoWeld actuators.

² At weld force ³ Weight varies with choice of feedback device and mounting options

⁴ Some exceptions, see GSWA user manual



SWA & SWB INTEGRATED MOTOR ACTUATOR

ENDURANCE TECHNOLOGY

Endurance Technology features are designed for maximum durability to provide extended service life.

A Tolomatic Design Principle





SWA/B_4

Tolomatic ... MAXIMUM DURABILITY

SKEWED MOTOR WINDINGS

Skewed motor windings provide minimal torque ripple for force repeatability and smooth linear motion

IP65

IP65 rating protects actuator from ingress of water, weld slag and other debris (static)

ADVANCED SCREW TECHNOLOGY

- Roller screws provide the highest thrust and life ratings available
- SWA: Highest DLR roller screw provides longest life



• SWB: Lower DLR roller screw, provides longer life than ball screws or inverted roller screws

WATER COOLING



• Option that is attached to any side of the actuator

•Allows increased duty cycle and increased jobs/hour

ROBOT & DRIVE/ CONTROLLER COMPATIBILITY

Compatible feedback, connector(s) and wiring to match the following robot & drive/controller manufacturers' cable dress packages

YOUR CHOICE:

- +ABB
- +Comau
- +Fanuc
- + Kawasaki
- + Kuka
- + Motoman/Yaskawa
- + Nachi
- + Rockwell Automation
- +Bosch-Rexroth
- + Emerson CT
- +WTC-Medar
- & more

FEEDBACK CHOICES

- Customer specified to robot manufacturer
- Multi-turn absolute encoder
- Resolver
- Digital encoder

HIGH THRUST BEARING

Provides complete support of screw and protects the feedback device from linear forces

OPTIONS

BRAKE WATER COOLING REAR TRUNNION MOUNTING



SWA/B_5

ServoWeld SWA & SWB - Integrated Motor Actuator

	SERIES SWA3 or SWB3 SWA4 or SWB4													
FRAME	mm		90.0						110.0					
SIZE	in		3.54						4.33					
MOTOR W	INDING		A3 / B3		A2 /	B2		A3	/ B3		A4 / B4			
NUT/	SCREW	RN04	RN05	RN10	RN05	RN10	RN04	RN05	RN05XR	RN10	RN04	RN05	RN05XR	RN10
§ SCREW LEAD	mm	4.0	5.0	10.0	5.0	10.0	4.0	5.0	5.0	10.0	4.0	5.0	5.0	10.0
PEAK	kN	11.1	11.1	5.8	14.5 / 12.8	7.3/6.4	17.8	14.7	22.1	11.1	17.8	14.7	24.0	17.8
FORCE	lbf	2500	2500	1306	3261/2882	1630/1441	4000	3300	4958	2500	4000	3300	5395	4000
MAX.	mm/sec	234	292	584	292	584	234	292	292	584	234	292	292	584
VELOCITY	in/sec	9.2	11.5	23.0	11.5	23.0	9.2	11.5	11.5	23.0	9.2	11.5	11.5	23.0
SWA SCREW DLR	kN	41.1	53.6	47.2	73.3	76.4	67.2	73.3	91.74	76.4	67.2	73.3	91.7	76.4
(DYNAMIC LOAD RATING)	lbf	9240	12050	10611	16479	17175	15107	16479	20624	17175	15107	16479	20624	17175
SWB SCREW DLR	kN	24.25	31.63	27.85	43.25	45.07	39.65	43.25	_	45.07	39.65	43.25	_	45.07
(DYNAMIC LOAD RATING)	lbf	5452	7110	6260	9723	10133	8913	9723	_	10133	8913	9723	_	10133
NOMINAL Back	N	436	347	173	405	205	507	405	405	205	507	405	405	205
DRIVE Force	lbf	98	78	39	91	46	114	91	91	46	114	91	91	46
WEIGHT*	kg	7.80	7.80	7.80	11.25	11.25	12.29	12.29	12.29	12.29	14.16	14.16	14.16	14.16
WEIGHT	lbf	17.2	17.2	17.2	24.8	24.8	27.1	27.1	27.1	27.1	31.2	31.2	31.2	31.2
STROKE	mm	150	150	150	150	150	150	150	150	150	150	150	150	150
STROKE	in	6	6	6	6	6	6	6	6	6	6	6	6	6
BASE	kg-cm ²	4.8997	4.8997	4.8997	8.1108	8.1108	9.7864	9.7864	9.7864	9.7864	11.4073	11.4073	11.4073	11.4073
INERTIA	lb-in	1.6723	1.6723	1.6723	2.7716	2.7716	3.3442	3.3442	3.3442	3.3442	3.8966	3.8966	3.8966	3.8966
AMBIENT TEMP **	°C						С) to 50						
RANGE	°F						_	2 to 122						
IP RATING						Stan	dard IP6	5 (static)						
AGENCY Listings						CE	ւ(Միս	is 🚺	P 65					

Table 1: Performance & Mechanical Specifications:

*Weight varies per feedback device or mounting option. See table below for details.

**From 0-10°C (32-50°F), additional startup procedure may be required for optimal performance. See user manual for details. §NOTE: Screw/Lead Accuracy: 0.023 mm/300 mm; 0.0009 in/ft

Table 2	2:		Weight Adder								
		Water	Rear		FE	EDBACK OP	TION				
		Cooling	Trunnion	F1	F2	A1	K1***	W1			
SW_3	kg	0.36	0.10	0.3	0.77	0.59	1.27	1.03			
300_3	lb	0.80	0.22	0.65	1.70	1.30	2.80	2.26			
SW_4	kg	0.52	0.24	0.3	0.48	0.64	1.34	0.72			
300_4	lb	1.15	0.52	0.65	1.05	1.41	2.96	1.59			

***Weight adder for K1 option includes weight of brake



ServoWeld SWA & SWB - Integrated Motor Actuator

Table 3: Motor Specifications:

		SERIES	SN	_3	SW_4								
	MOTOR V	VINDING	A3	B3	A2	B2	A 3	B3	A 4	B4			
	ICTANT (V.)	N-m/A Peak	0.62	1.21	0.52	0.90	0.61	1.20	0.64	1.29			
TORQUE CON	ISTANT (NE)	in-Ib/A Peak	5.5	10.7	4.6	8.0	5.4	10.6	5.7	11.4			
VOLTAGE CON	STANT (K _e)	V/Krpm Peak	79.8	154	66.1	107.2	78.1	153.1	81.1	162.3			
	No Water	N-m	4.4	4.3	5.5	4.9	8.4	8.5	14.6	14.6			
CONTINUOUS	Cooling	in-lb	39	38	48.8	43.0	74	75	129	129			
STALL TORQUE	With Water	N-m	8.8	8.6	11.0	9.7	16.7	17.0	20.8	20.8			
	Cooling	in-lb	78	76	97.6	86	148	150	184	184			
CONTINUOUS	No Water Cooling	A_{RMS}	5	2.5	7.5	3.8	9.7	5.0	16	8			
STALL CURRENT	With Water Cooling	$A_{_{\mathrm{RMS}}}$	10.0	5.0	15.0	7.6	19.4	10.0	23	12			
DE	AK TORQUE	N-m	13.2	12.9	16.5	14.6	25.1	25.4	43.7	43.7			
PE	AK TURQUE	in-lb	117	114	146	129	222	225	387	387			
PEA	K CURRENT	A_{RMS}	15	7.5	22.5	11.4	29.1	15.0	48	24			
R	ESISTANCE	Ohms	2.07	8.3	0.9	4.2	0.58	2.32	0.36	1.46			
IN	IDUCTANCE	mH	3.8	15	3.65	15.7	2.75	11.5	2.04	8.9			
NC). OF POLES					8	3						
BL	IS VOLTAGE	V_{RMS}	230	460	230	460	230	460	230	460			
SPEED	@ RATED V	RPM		3,500									

SIDE LOADING

Some weld gun designs may subject the actuator to excessive side loading reducing overall service life. Measures are required, especially in "C" style designs, to limit side loading. For life optimization Tolomatic recommends side loads less than indicated in the graph below.

SW_SIDE LOAD SPECIFICATIONS at 150 mm (6 in)





Table 4: Brake Specifications:

	SERIES	SW_3	SW_4
ROTOR	gm-cm ²	73	239
INERTIA	oz-in²	0.400	1.307
CURRENT	Amp	0.43	0.67
HOLDING	N-m	4.0	10.0
TORQUE	in-lb	35	89
ENGAGE Time	mSec	40	25
DISENGAGE TIME	mSec	50	50
VOLTAGE	Vdc	24	24

BRAKE CONSIDERATIONS

In all vertical application an un-powered SWA will require a brake to maintain position. Tolomatic recommends that the nominal

back drive force specification (listed in Table 1) be used for reference only. Back drive force is subject to change throughout the life of the actuator, due to mechanical break in, ambient temperature, and duty cycle variation.

A brake can be used with the actuator to keep it from backdriving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when un-powered. Brake v

NOTE: The optional Spring-Applied / Electronically-Released Brake requires 24V power.



Brake will increase actuator length and weight, see Table 2 (K1).



SWA & SWB Dimensions

Table 5: Dimensions



	SW_3	SW_4						
F	90.0	110.0						
G	60.000	64.500						
Η	2.8	3.4						
J	30.135	34.926						
K	M8 x 1.25	M8 x 1.25						
L	16.0	13.0						
Μ	36.0	29.072						
Ν	69.0	79.874						
Р	M12 x 1.25	M20 x 1.5						
R	22.2	25.9						
S	17.6	19.1						
Τ	273.0	321.0						
U**	53.3	66.7						
V*	15.98	20.0						
W*	16.0	20.1						
X	-	8.052/8.026						
Y	-	12.7						
Ζ	-	85.00						
AA	-	94.01/93.95						
AB	-	12.09/12.04						
AC	-	6.00						
AD	-	M10 x 1.5						
AE	_	16.00						
AF	_	50.00						
AG	_	15.00						

*for Trunnion Option **for Water Cooling Option Dimensions in millimeters

	SW_3	SW_4
F	3.54	4.33
G	2.3622	2.5394
Η	0.11	0.13
J	1.1864	1.3750
Κ	M8 x 1.25	M8 x 1.25
L	0.63	0.51
Μ	1.42	1.1446
Ν	2.72	3.1446
Ρ	M12 x 1.25	M20 x 1.5
R	0.88	1.02
S	0.69	0.75
Т	10.75	12.64
U**	2.10	2.63
۷*	0.629	0.787
W*	0.63	0.79
X	-	0.3170/0.3160
Y	-	0.50
Ζ	-	3.346
AA	_	3.701/3.699
AB	_	0.476/0.474
AC	-	0.236
AD	-	M10 x 1.5
AE	_	0.630
AF	_	1.969
AG	_	0.591

*for Trunnion Option **for Water Cooling Option Dimensions in inches

					SW_3			SW_4					
Motor Winding	Feedback		A1	F1	F2	K1	W1	A1	F1	F2	K1	W1	
A,B 2,3	w/o Brake		350.5	343.5	366.5	**	387.3	402.9	395.4	418.0	**	439.3	
A,B 2,3	w/ Brake		373.9	375.5	**	377.7	401.6	427.1	433.9	**	422.2	453.5	
A,B 4	w/o Brake	A	-	-	-	-	-	410.7	403.2	425.8	**	447.1	
A,B 4	w/ Brake		-	-	-	-	-	434.9	441.7	**	423.3	461.3	
		В	90.0	90.0	110.0	90.0	110.0	110.0	110.0	110.0	110.0	110.0	
		C	85.3	71.6	78.4	86.4	78.0	94.1	78.4	78.4	96.4	78.0	
		D*	95.2	95.2	123.0	95.2	123.0	123.0	123.0	123.0	123.0	123.0	
	Feedback Connector Code/Type		A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX	A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX	
*for Truppic	n Ontion *	*00	staat Tala	matia for	additional	informativ	n Dim	anaiana	in millim	atoro			

*for Trunnion Option *Contact Tolomatic for additional information

Dimensions in millimeters

					SW_3					SW_4		
Motor Winding	Feedb	ack	A1	F1	F2	K1	W1	A1	F1	F2	K1	W1
A,B 2,3	w/o Brake		13.80	13.52	14.43	**	15.25	15.86	15.57	16.46	**	17.29
A,B 2,3	w/ Brake	A	14.72	14.78	**	14.87	15.81	16.81	17.08	**	16.62	17.85
A,B 4	w/o Brake		-	-	-	-	-	16.17	15.87	16.76	**	17.60
A,B 4	w/ Brake		-	-	-	-	-	17.12	17.39	**	16.67	18.16
		В	3.54	3.54	4.33	3.54	4.33	4.33	4.33	4.33	4.33	4.33
		C	3.36	2.82	3.09	3.40	3.07	3.71	3.09	3.09	3.80	3.07
		D*	3.75	3.75	4.84	3.75	4.84	4.84	4.84	4.84	4.84	4.84
	ack Connecto ode/Type	r	A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX	A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX

*for Trunnion Option

**Contact Tolomatic for additional information

Dimensions in inches

SWA/B 8





EVERY SERVOWELD ACTUATOR HAS TO PASS RIGOROUS TESTING AT OUR FACTORY.

We verify the performance of each individual unit before delivery to ensure they conform to Tolomatic's high standard of performance.



Functional unit testing for hundreds of cycles quantifies stroke, length, torque under no load, input current vs force standard deviation.

	FOIO COLLEN	natic	New Test	Sont Test	Cancel Test	Part Result	Machine Setup	Manual Screen	
fork Order 09791 odel AA33		Assembly Number 27340200 itch Voltage Sta 108 LV 3	ick.	W 11 10:16 AW			Operater		
Curr	eet Step: Test (Complete, Test Time -	111.2003424 se	conda. Click Print	to print report.				
				Test Resul	t Pass				
Stoke		Max Force Av	rage	Max Force Std Dev				Torque SM De	ev.
Min (iii)	5.8	Min (Ibs)	695	Max (lbs)	18	Min (oz in)	70	Max (oz in)	9
Max (in)	6.5	Max (ibs)	1090	Actual (bs)	6.91	Max (oz in)	125	Extend (ozin)	121
Actual (in)	6.11	Ave Act. (ba)	065.48	Result	Free	Extend (oc in)		Retract (ozin)	1.30
	Pasa	Result	Pilm	1		Retract (oz in)		Result	2000
Result						Result	Page		

Testing parameter results in progress for the Functional Test procedure.



Final system test ensures the feedback device is properly aligned with the ServoWeld motor poles.

High POT (High Potential/High Voltage Test)

This standard electric motor test procedure is a 3-part test that checks the insulation system of the assembly to verify proper armature and thermal wire insulation.

2. Electronic phasing of ServoWeld[®] and feedback device (Encoder, Resolver, Feedback Device)

Using a fixed current and a specially designed fixture the feedback device is physically and electronically aligned relative to the phasing of the Tolomatic motor.

3. Functional Testing

Performed with Tolomatic motion control components and dedicated data acquisition equipment. Operated for hundred of cycles, this test quantifies these parameters - stroke length, torque under no load, input current vs force average, input current vs force standard deviation - using an electronic load cell in conjunction with data acquisition equipment.

4. Tolomatic System Test

Using a single-axis control unit the test ensures that the feedback device is properly aligned with the poles of the Tolomatic motor.



ServoWeld Application Guidelines

- **SIDE LOADING:** Weld gun designs may subject the actuator to excessive side loading, reducing overall service life. The GSWA33 and CSW(x) Guided actuators will accommodate side loading caused by the mass of the electrode, misaligned weld tips and tip skid. For other ServoWeld configurations additional measures are required to limit side loading, especially in "C" style gun designs. For maximum service life, external guiding is recommended to minimize side loading to the thrust rod and provide consist weld gun alignment throughout the service life. Reference the side load capacity charts in the GSWA, SWA/SWB, and CSW(x) manuals and/or brochures.
- **THRUST ROD WIPER/SCRAPER:** For maximum service life, measures should be taken to reduce/eliminate contamination, weld slag, and water in the thrust rod wiper/scraper interface area. Implementation of industrial thrust rod boot and/or deflective device can be effectively utilized in this area.
- **CABLES:** Shielded power & feedback cables are recommended to minimize electrical noise/grounding issues. Electrical noise or inadequate grounding can corrupt the feedback device signal.
- **RSW SERVO SYSTEM CALIBRATION:** RSW weld gun servo system consists of robot 7th axis amplifier, robot feedback device, robot RSW software, weld gun chassis, & ServoWeld.

For optimal RSW weld gun servo system performance the calibration process should include maximum weld tip force from the production weld schedule, tip dress force, and multiple weld tip forces in-between. Utilizing all the available robot manufacturer force table inputs will provide best RSW weld gun servo system performance. The same weld tip part contact speed should be used for both RSW weld gun servo system calibration and production weld schedule.

WELD TIP / PART CONTACT SPEED: Tolomatic testing confirms the highest ServoWeld repeatability (**INPUT**

CURRENT verses **OUTPUT FORCE**) at a weld tip part contact speed of 25mm/second or less. Speeds greater than 25mm/second can create "impact contribution" to the weld force. This impact contribution to the weld force deteriorates prior to completion of the weld cycle.

- **ROBOT CARRIED APPLICATIONS:** Robot carried RSW gun applications have reduced exposure to water pooling/water ingression by virtue of the continuous robot movement and various RSW gun positions. In addition, in robot carried applications positioning of the RSW gun can be programmed as part of the weld cap change program/routine to eliminate ServoWeld exposure to water. (ServoWeld above weld caps)
- **ROBOT MANUFACTURER SERVO FILE:** Robot manufacturer servo parameter files for operation of ServoWeld are available only from the robot manufacturer. Each robot manufacturer creates 3rd party motor servo parameter files, validates operation of ServoWeld via their 7th axis, and maintains servo motor parameter file for operation of ServoWeld.
- **TOOL CHANGER APPLICATIONS:** Weld gun storage fixture in cell should position weld gun so movable electrode is not loading ServoWeld thrust rod - back driving the ServoWeld. Weld gun tips should be positioned to weld gun closed at low force prior to disconnect from robot/tool changer. Consider ServoWeld configured with integral brake option.
- **FIXED / PEDESTAL APPLICATIONS:** One of the more challenging RSW applications is a pedestal RSW gun, ServoWeld mounted vertical thrust rod up. Measures should be taken to reduce and/or eliminate the ServoWeld to water exposure, water pooling/spray in the access areas of the ServoWeld unit to maximize overall service life.



ServoWeld SWA & SWB Integrated Motor Actuators



XX Special

Tolomatic

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SWA/B_11

The Tolomatic Difference Expect More From the Industry Leader:



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